## FIG. 1

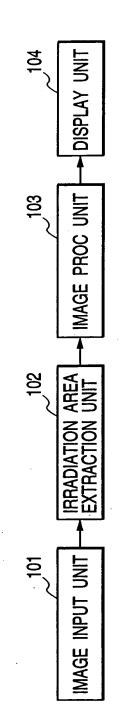
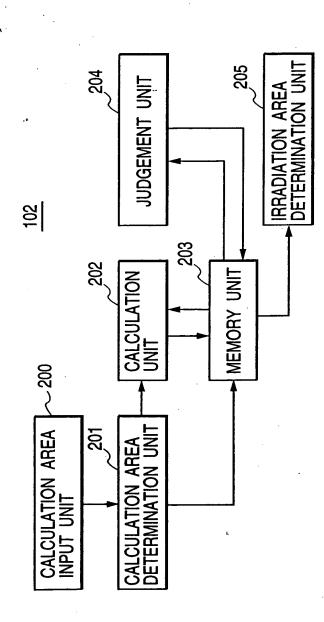
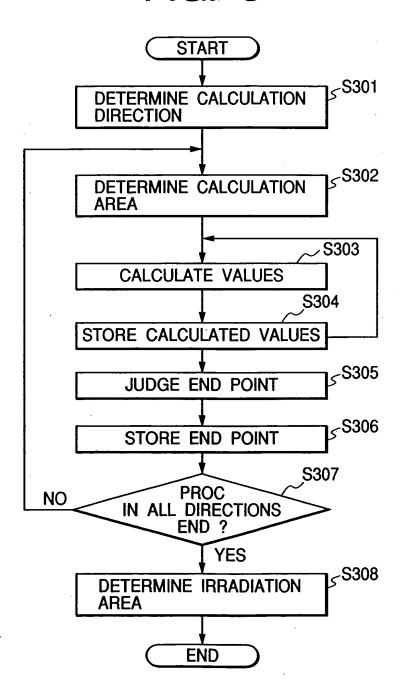


FIG. 2



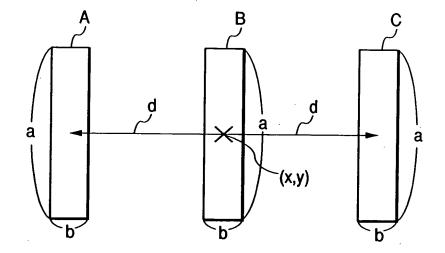
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FIG. 3



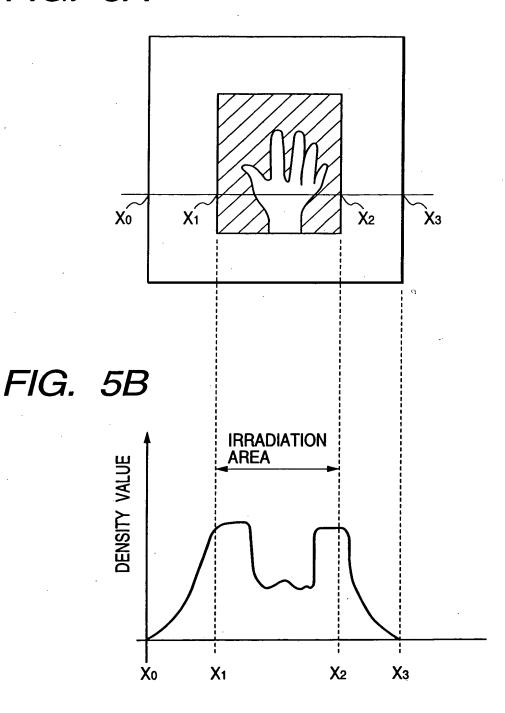
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FIG. 4



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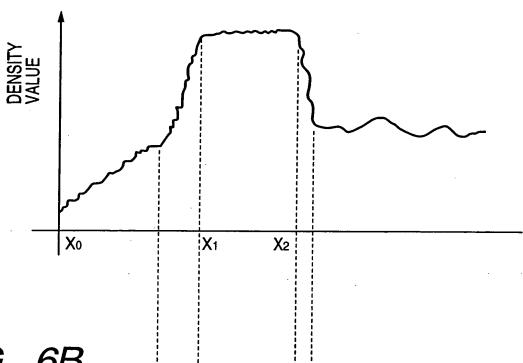
FIG. 5A

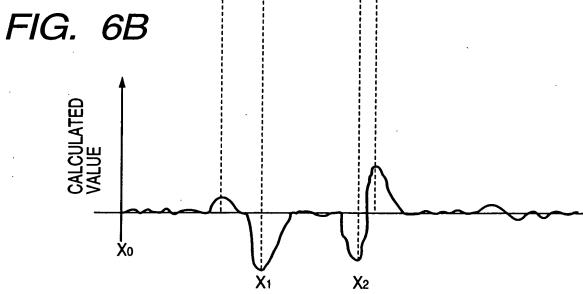


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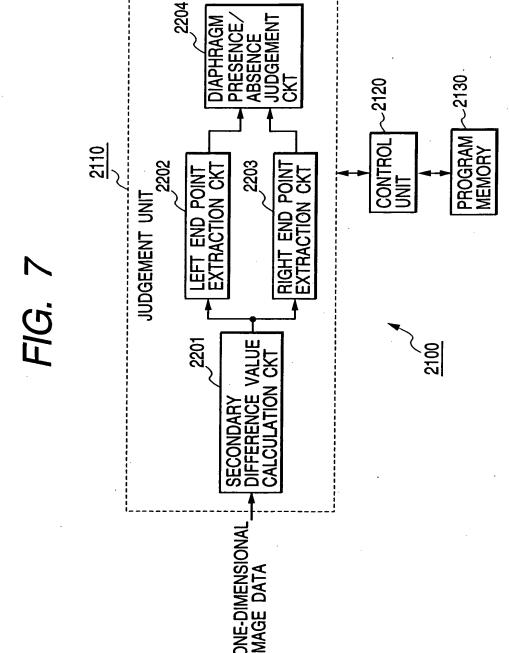
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FIG. 6A





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FIG. 8

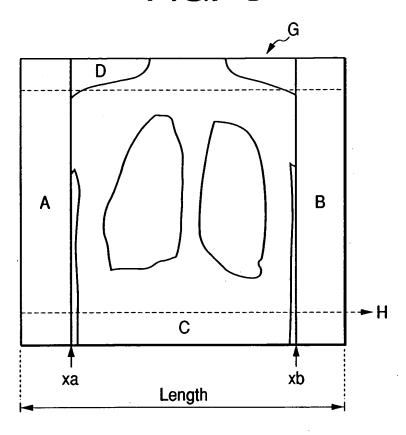
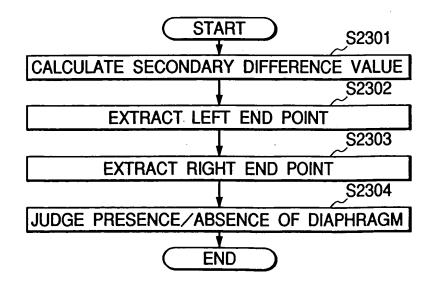


FIG. 9



The death stand that the limit that the stand that

FIG. 10

8 / 18 2130 PROGRAM MEMORY 2120 CONTROL 2140 ~2406  $\sim$ 2407  $\sim$ 2408  $\sim$ 2409 2403 JUDGEMENT UNIT RIGHT END POINT EXTRACTION CKT SECOND JUDGEMENT CKT COORDINATE VARIANCE CALCULATION CKT AVERAGE COORDINATE CALCULATION CKT FIRST JUDGEMENT CKT MEMORY CKT 2402 LEFT END POINT EXTRACTION 2404 SECONDARY
DIFFERENCE
VALUE
CALCULATION CKT INDICATION CKT ONE-DIMENSIONAI IMAGE DATA

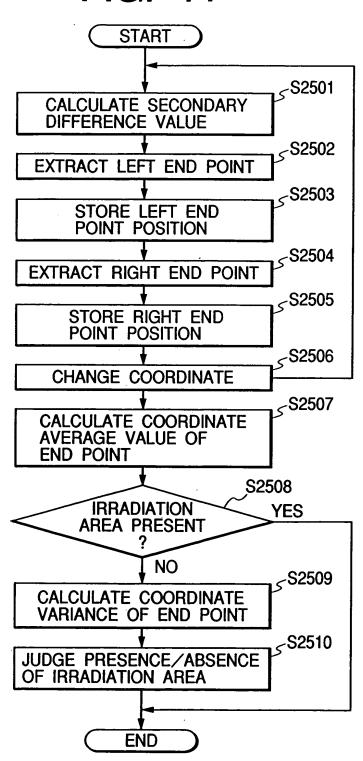
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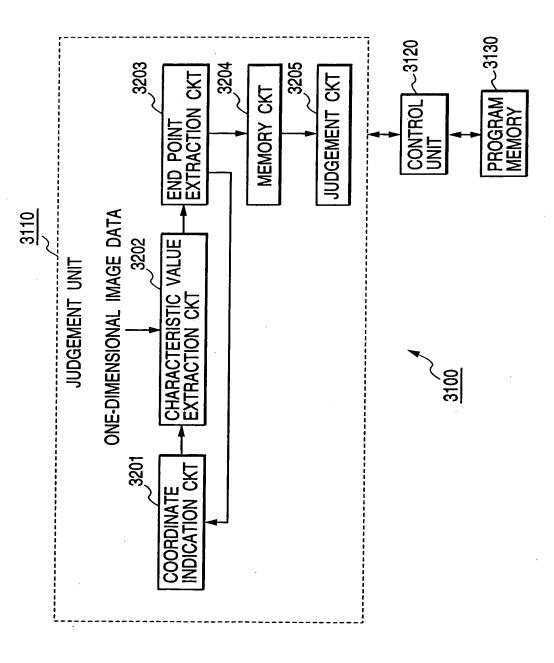
## FIG. 11



The second state of the state o

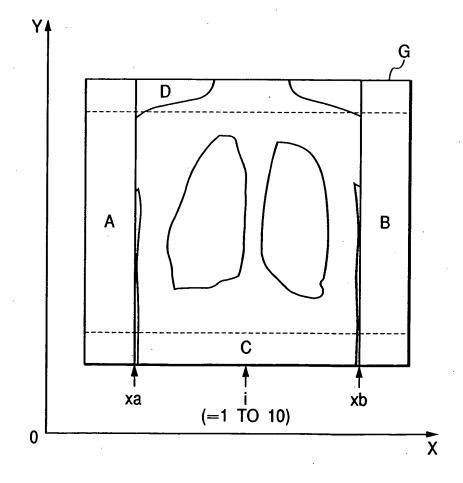
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FIG. 12



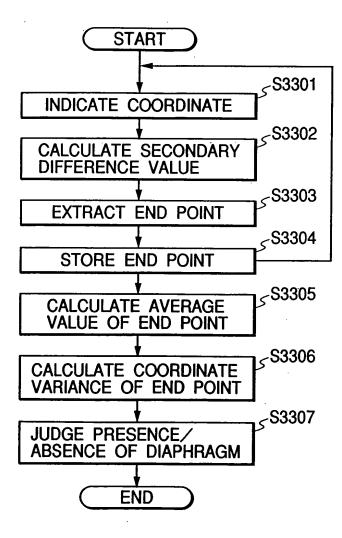
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FIG. 13



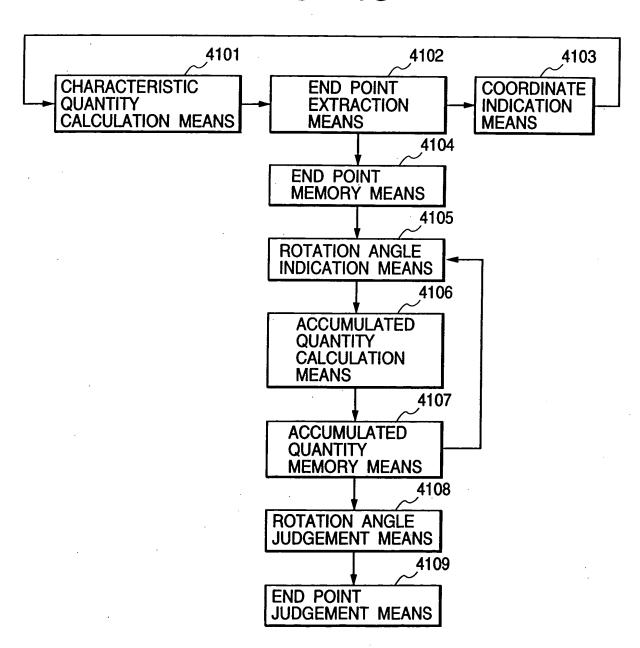
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## FIG. 14



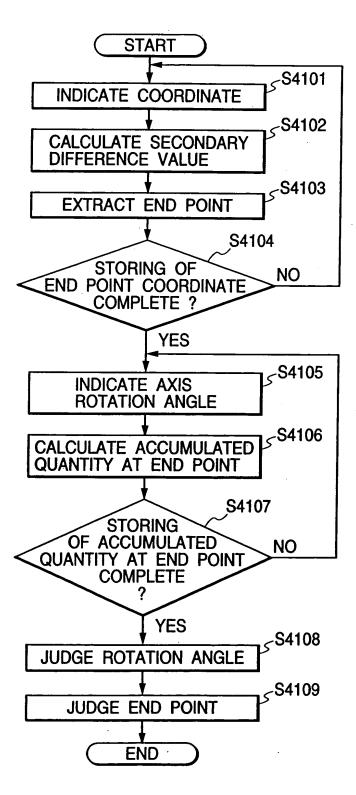
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FIG. 15



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FIG. 16



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FIG. 17

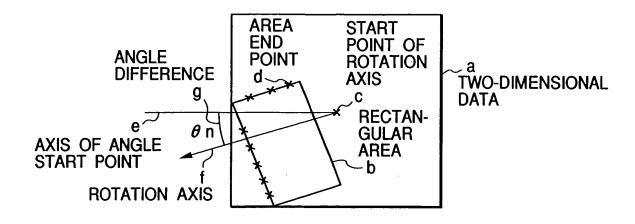
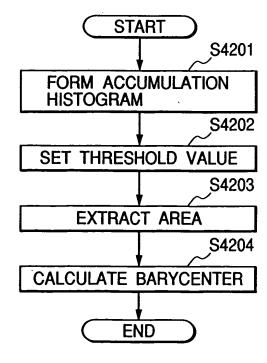


FIG. 18



and the first first the first state of the first st

FIG. 19

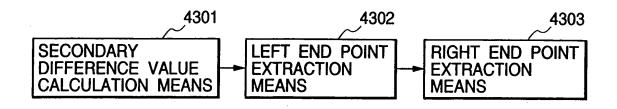
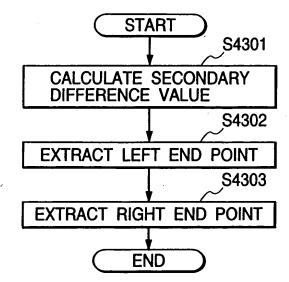
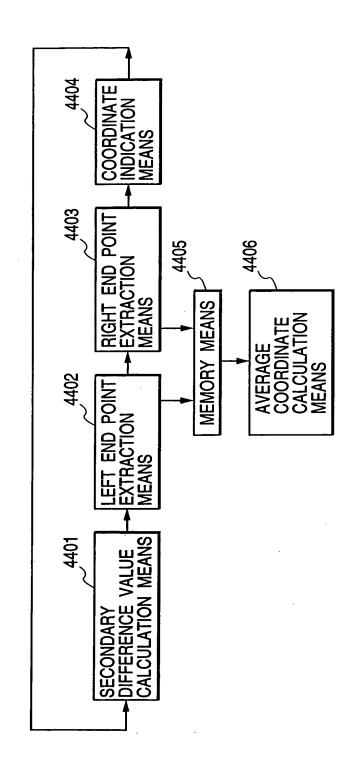


FIG. 20



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FIG 21



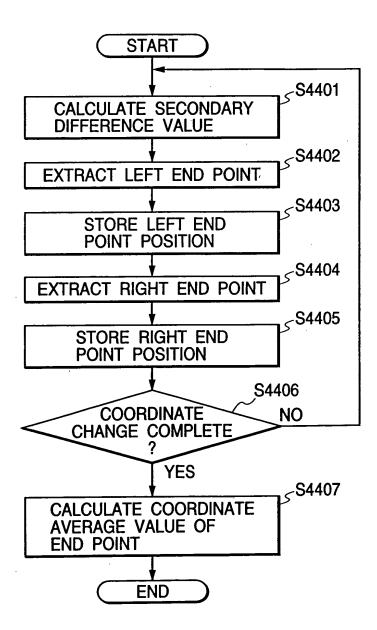
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FIG. 22



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